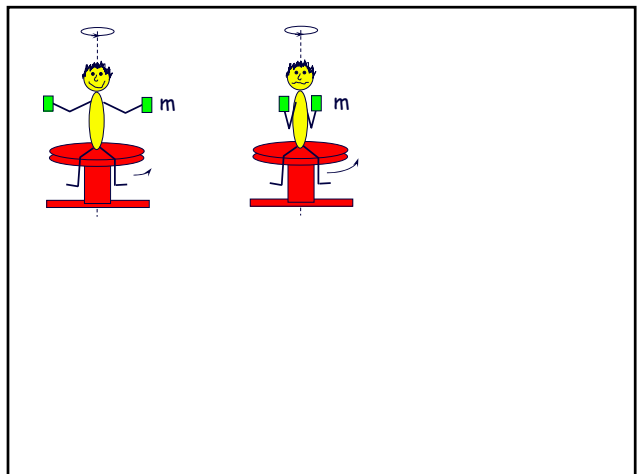
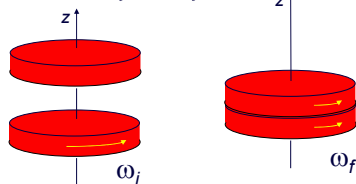


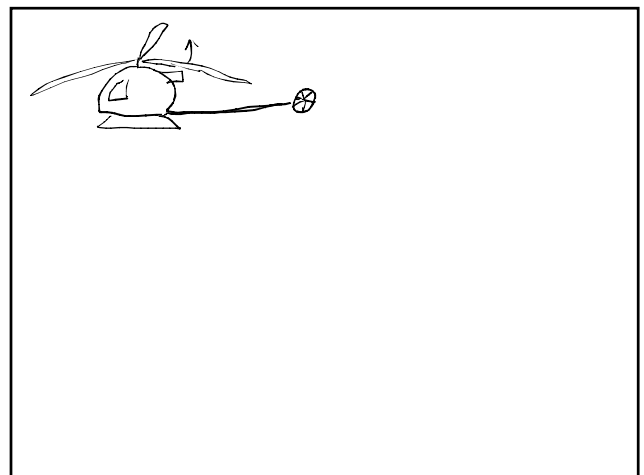
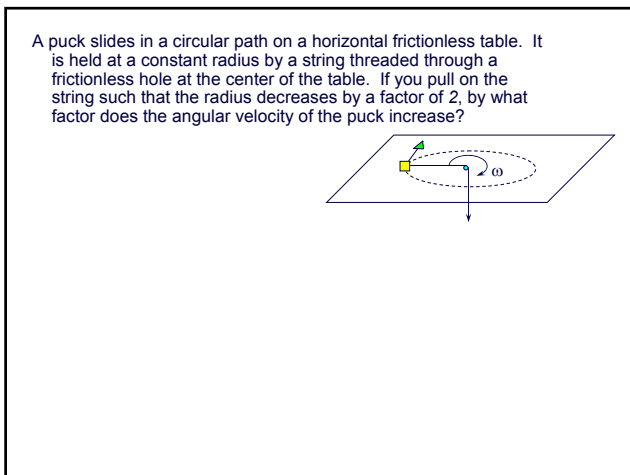
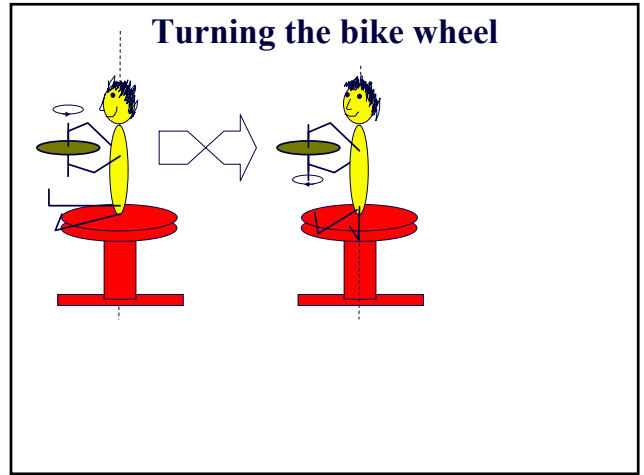
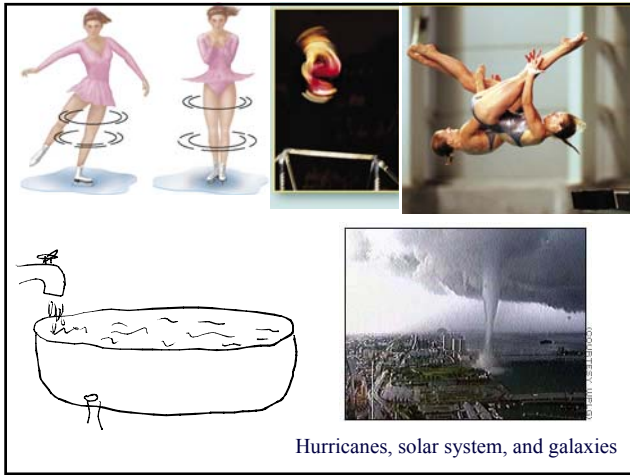
## Review

- $K_{\text{rotation}} = \frac{1}{2} I \omega^2$
- Torque = Force that causes rotation
  - Very loosely speaking: “angular force”
- Equilibrium
  - $\Sigma F = 0$
  - $\Sigma \tau = 0$

- We had angular everything, displacement, velocity, acceleration, energy and torque
- How about angular momentum?
  - Not for completeness, but for some possibly neat things
  - $F\Delta t = \Delta p$
  - If impulse = 0 (or  $F = 0$ ), momentum is conserved
  - $rF\Delta t = r\Delta(mv) = \Delta(rmv)$
  - If torque  $rF = 0$ ,  $rmv$  is conserved
  - Call it angular momentum (units:  $\text{kg}\cdot\text{m}^2/\text{s}$ )
  - Given a choice, how do we define angular momentum?
    - Momentum  $p = mv$
- $rmv = (mr^2)(v/r)$   
 $= I \omega$

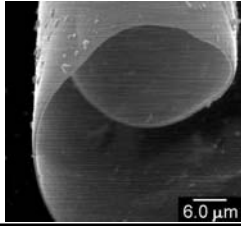
- A disk of mass  $M$  and radius  $R$  rotates around the  $z$  axis with angular velocity  $\omega_i$ . A second identical disk, initially not rotating, is dropped on top of the first. There is friction between the disks, and eventually they rotate together with angular velocity  $\omega_f$ . Find  $\omega_f$ .





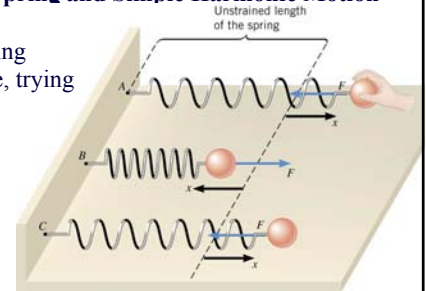
## Chapter 10 Simple Harmonic Motion and Elasticity

- Where are they?
- Harmonic Motion
  - Sound, molecular vibrations, all music instruments, light...
  - Everything in quantum physics (there is no such a thing as matter; all matters are combinations of particles and waves)
- Elasticity
  - Everything. There is nothing that is rigid, not even crystals



## 10.1 The Ideal Spring and Simple Harmonic Motion

- The force of a spring is a restoring force, trying to get back to the relaxed position



- For a spring
  - $F_x = -kx$
  - $x$ : displacement from relaxed position
  - $k$  is the constant of proportionality. (often called “spring constant”)
- **Hooke’s Law:**
- The force exerted by a spring is proportional to the distance the spring is stretched or compressed from its relaxed position.

